

Satisfaction Equilibrium

Definition, Learning Dynamics and Applications

Samir M. Perlaza

Alcatel Lucent Chair in Flexible Radio at Supelec

Joint work with **H. Tembine** from SUPELEC, Telecom Dept. and **S. Lasaulce** from LSS-CNRS-SUPELEC and **M. Debbah** from Alcatel Lucent Chair in Flexible Radio at Supelec

Workshop on Algorithmic Game Theory: Dynamics and Convergence in Distributed Systems
AlgoGT 2011.

June, 20-21th 2011, Grenoble, France

Outline

Motivation

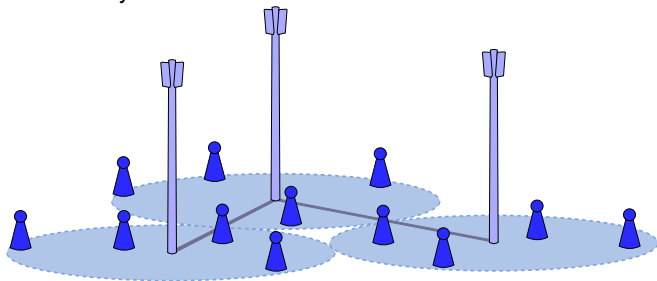
Satisfaction Equilibrium (SE)

Learning Satisfaction Equilibrium

Conclusions

Motivation

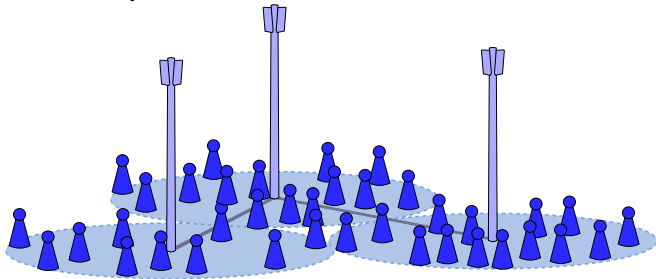
Classical Cellular Systems



- Base Stations (BS) determines optimal Tx/Rx configurations.
- Terminals are not necessarily cognitive radios.

Motivation

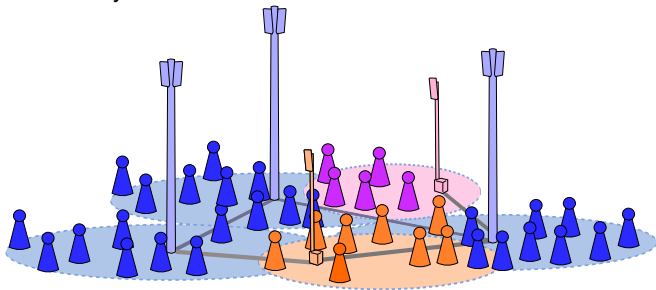
Classical Cellular Systems



- Explosion of number of communicating radio devices.
- Radio devices become more flexible: SDR, cognitive radio.

Motivation

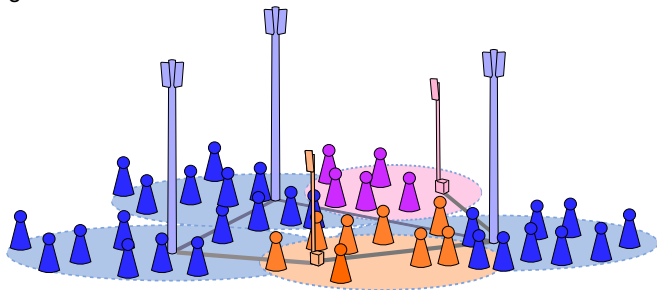
Today's Cellular Systems



- Need of additional infrastructure: femtocells, smallcells, relays, etc.
- Decentralized/uncoordinated approach.
- **How to provide QoS?**

Motivation

Modeling Decentralized Networks as Games



$$\mathcal{G} = (\mathcal{K}, \{\mathcal{A}_k\}_{k \in \mathcal{K}}, \{u_k\}_{k \in \mathcal{K}})$$

- **Players:** Set $\mathcal{K} = \{1, \dots, K\}$ of transmitters and/or receivers.
- **Actions:** Set \mathcal{A}_k of transmission/receive configurations of player $k \in \mathcal{K}$.
- **Utility function:** $u_k : \mathcal{A}_1 \times \dots \times \mathcal{A}_K \rightarrow \mathbb{R}$ is a performance metric of player k .

Nash Equilibrium

J. F. Nash, "Equilibrium points in n-person games", Proceedings of the National Academy of Sciences of the United States of America, vol. 36, no. 1, pp. 48-49, 1950.

Definition (Nash Equilibrium (Nash-1950))

An action profile $\mathbf{a}^* \in \mathcal{A}$ is a NE of \mathcal{G} , if $\forall k \in \mathcal{K}$ and $\forall \mathbf{a}'_k \in \mathcal{A}_k$,

$$u_k(\mathbf{a}^*_k, \mathbf{a}^*_{-k}) \geq u_k(\mathbf{a}'_k, \mathbf{a}^*_{-k}). \quad (1)$$

- Each player's action is **optimal** w.r.t. the actions of all the other players.
- What if it is required that $u_k(\mathbf{a}^*_k, \mathbf{a}^*_{-k}) > \Gamma_k$?

Nash Equilibrium

J. F. Nash, "Equilibrium points in n-person games", Proceedings of the National Academy of Sciences of the United States of America, vol. 36, no. 1, pp. 48-49, 1950.

Definition (Nash Equilibrium (Nash-1950))

An action profile $\mathbf{a}^* \in \mathcal{A}$ is a NE of \mathcal{G} , if $\forall k \in \mathcal{K}$ and $\forall \mathbf{a}'_k \in \mathcal{A}_k$,

$$u_k(\mathbf{a}^*_k, \mathbf{a}^*_{-k}) \geq u_k(\mathbf{a}'_k, \mathbf{a}^*_{-k}). \quad (1)$$

- Each player's action is **optimal** w.r.t. the actions of all the other players.
- What if it is required that $u_k(\mathbf{a}^*_k, \mathbf{a}^*_{-k}) > \Gamma_k$?

Nash Equilibrium

J. F. Nash, "Equilibrium points in n-person games", Proceedings of the National Academy of Sciences of the United States of America, vol. 36, no. 1, pp. 48-49, 1950.

Definition (Nash Equilibrium (Nash-1950))

An action profile $\mathbf{a}^* \in \mathcal{A}$ is a NE of \mathcal{G} , if $\forall k \in \mathcal{K}$ and $\forall \mathbf{a}'_k \in \mathcal{A}_k$,

$$u_k(\mathbf{a}_k^*, \mathbf{a}_{-k}^*) \geq u_k(\mathbf{a}'_k, \mathbf{a}_{-k}^*). \quad (1)$$

- Each player's action is **optimal** w.r.t. the actions of all the other players.
- What if it is required that $u_k(\mathbf{a}_k^*, \mathbf{a}_{-k}^*) > \Gamma_k$?

Generalized Nash Equilibrium

G. Debreu, "A social equilibrium existence theorem," Proceedings of the National Academy of Sciences of the United States of America, vol. 38, no. 10, pp. 886-893, October 1952.

- The set of each player's actions is **constrained**.

$$f_k : \mathcal{A}_{-k} \rightarrow 2^{\mathcal{A}_k} \quad (2)$$

- Consider the **extended version** of the normal form:

$$\tilde{\mathcal{G}} = (\mathcal{K}, \{\mathcal{A}_k\}_{k \in \mathcal{K}}, \{u_k\}_{k \in \mathcal{K}}, \{f_k\}_{k \in \mathcal{K}}). \quad (3)$$

Definition (Generalized NE (Debreu-1952))

An action profile $\mathbf{a}^* \in \mathcal{A}$ is a *generalized Nash equilibrium (GNE)* of $\tilde{\mathcal{G}}$, if $\forall k \in \mathcal{K}$ and $\forall \mathbf{a}_k \in f_k(\mathbf{a}_{-k}^*)$,

$$u_k(\mathbf{a}_k^*, \mathbf{a}_{-k}^*) \geq u_k(\mathbf{a}_k, \mathbf{a}_{-k}^*), \text{ and} \quad (4)$$

$$\forall k \in \mathcal{K}, \quad \mathbf{a}_k^* \in f_k(\mathbf{a}_{-k}^*) \quad (5)$$

Generalized Nash Equilibrium

G. Debreu, "A social equilibrium existence theorem," Proceedings of the National Academy of Sciences of the United States of America, vol. 38, no. 10, pp. 886-893, October 1952.

- The set of each player's actions is **constrained**.

$$f_k : \mathcal{A}_{-k} \rightarrow 2^{\mathcal{A}_k} \quad (2)$$

- Consider the **extended version** of the normal form:

$$\tilde{\mathcal{G}} = (\mathcal{K}, \{\mathcal{A}_k\}_{k \in \mathcal{K}}, \{u_k\}_{k \in \mathcal{K}}, \{f_k\}_{k \in \mathcal{K}}). \quad (3)$$

Definition (Generalized NE (Debreu-1952))

An action profile $\mathbf{a}^* \in \mathcal{A}$ is a generalized Nash equilibrium (GNE) of $\tilde{\mathcal{G}}$, if $\forall k \in \mathcal{K}$ and $\forall \mathbf{a}_k \in f_k(\mathbf{a}_{-k}^*)$,

$$u_k(\mathbf{a}_k^*, \mathbf{a}_{-k}^*) \geq u_k(\mathbf{a}_k, \mathbf{a}_{-k}^*), \text{ and} \quad (4)$$

$$\forall k \in \mathcal{K}, \quad \mathbf{a}_k^* \in f_k(\mathbf{a}_{-k}^*) \quad (5)$$

Generalized Nash Equilibrium

G. Debreu, "A social equilibrium existence theorem," Proceedings of the National Academy of Sciences of the United States of America, vol. 38, no. 10, pp. 886-893, October 1952.

- The set of each player's actions is **constrained**.

$$f_k : \mathcal{A}_{-k} \rightarrow 2^{\mathcal{A}_k} \quad (2)$$

- Consider the **extended version** of the normal form:

$$\tilde{\mathcal{G}} = (\mathcal{K}, \{\mathcal{A}_k\}_{k \in \mathcal{K}}, \{u_k\}_{k \in \mathcal{K}}, \{f_k\}_{k \in \mathcal{K}}). \quad (3)$$

Definition (Generalized NE (Debreu-1952))

An action profile $\mathbf{a}^* \in \mathcal{A}$ is a *generalized Nash equilibrium (GNE)* of $\tilde{\mathcal{G}}$, if $\forall k \in \mathcal{K}$ and $\forall \mathbf{a}_k \in f_k(\mathbf{a}_{-k}^*)$,

$$u_k(\mathbf{a}_k^*, \mathbf{a}_{-k}^*) \geq u_k(\mathbf{a}_k, \mathbf{a}_{-k}^*), \text{ and} \quad (4)$$

$$\forall k \in \mathcal{K}, \quad \mathbf{a}_k^* \in f_k(\mathbf{a}_{-k}^*) \quad (5)$$

The Pertinence of Existing Equilibrium Concepts

S. Ross and B. Chaib-draa, "Satisfaction equilibrium : Achieving cooperation in incomplete information games," in the 19th Canadian Conf. on Artificial Intelligence, 2006.

- Do we really need to **maximize a performance metric**?
- What if we target the QoS satisfaction only?

The Pertinence of Existing Equilibrium Concepts

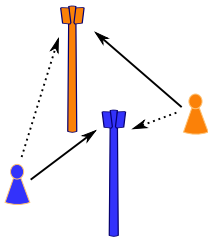
S. Ross and B. Chaib-draa, "Satisfaction equilibrium : Achieving cooperation in incomplete information games," in the 19th Canadian Conf. on Artificial Intelligence, 2006.

- Do we really need to **maximize a performance metric**?
- What if we **target the QoS satisfaction** only?

Example 1

2 Tx-Rx Pairs Sharing 1 freq. band:

- **Minimum rate** required: Γ_k bps.
- N_k **Transmit Power Levels**.



$$\tilde{\mathcal{G}} = (\mathcal{K}, \{\mathcal{A}_k\}_{k \in \mathcal{K}}, \{u_k\}_{k \in \mathcal{K}}, \{f_k\}_{k \in \mathcal{K}})$$

- Players $\mathcal{K} = \{1, 2\}$.
- Actions: **Power Control**

$$\mathcal{A}_k = \{p_k^{(1)}, \dots, p_k^{(N_k)}\}.$$

- Utility Function

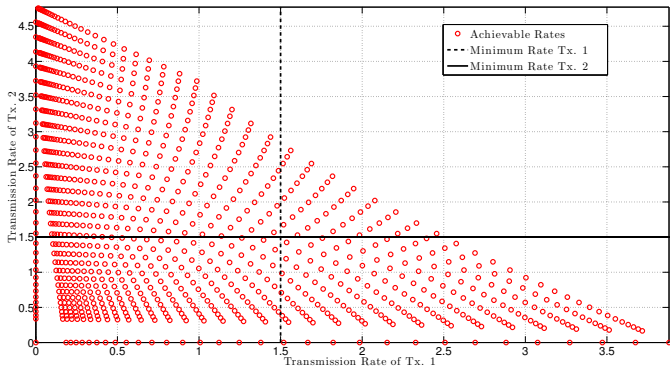
$$u_k(p_k, p_{-k}) = \log_2 \left(1 + \frac{p_k |h_{k,k}|^2}{\sigma_k^2 + \sum_{j \neq k} p_{-k} |h_{k,-k}|^2} \right) [\text{bps}],$$

- Constraints:

$$f_k(p_{-k}) = \{p_k \in \mathcal{A}_k : u_k(p_k, p_{-k}) \geq \Gamma_k\}$$

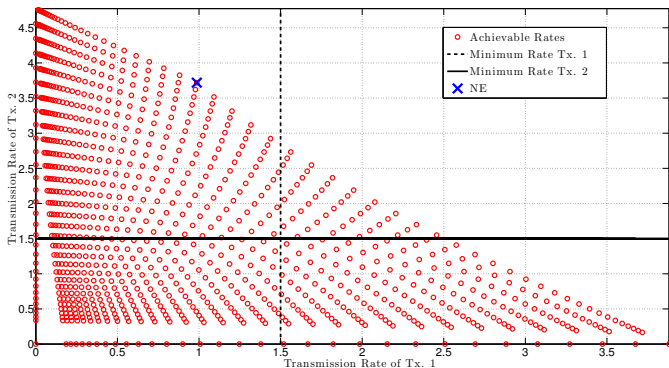
Example 1

Achievable Rates + Minimum Rates



Example 1

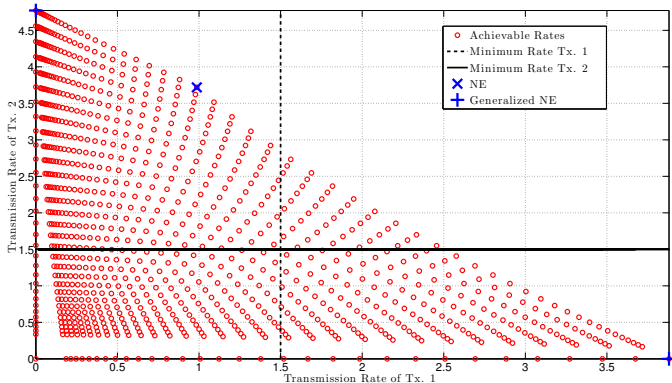
Achievable Rates + Minimum Rates + NE



At the NE, **only player 2 is satisfied.**

Example 1

Achievable Rates + Minimum Rates + NE + GNE



At a GNE, **either player 1 or player 2** are satisfied.

Our Contributions

A General Framework for Quality-Of-Service Provisioning in Decentralized Networks.

Perlaza, S. M. and Tembine, H. and Lasaulce, S. and Debbah, M., "A General Framework for Quality-Of-Service Provisioning in Decentralized Networks". Submitted to the IEEE Journal in Selected Topics in Signal Processing, Special Issue in Game Theory for Signal Processing. 2011

Perlaza, S. M. and Tembine, H. and Lasaulce, S. and M. Debbah, "Satisfaction equilibrium: A general framework for QoS provisioning in self-configuring networks," in the IEEE Global Communications Conference (GLOBECOM), Miami, USA, Dec. 2010.

Our Contributions

A General Framework for Quality-Of-Service Provisioning in Decentralized Networks.

Perlaza, S. M. and Tembine, H. and Lasaulce, S. and Debbah, M., "**A General Framework for Quality-Of-Service Provisioning in Decentralized Networks**". Submitted to the IEEE Journal in Selected Topics in Signal Processing. Special Issue in Game Theory for Signal Processing. 2011

Perlaza, S. M. and Tembine, H. and Lasaulce, S. and M. Debbah, "**Satisfaction equilibrium: A general framework for QoS provisioning in self-configuring networks,**" in the IEEE Global Communications Conference (GLOBECOM), Miami, USA, Dec. 2010.

Satisfaction Equilibrium

Perlaza, S. M. and Tembine, H. and Lasaulce, S. and M. Debbah, "Satisfaction equilibrium: A general framework for QoS provisioning in self-configuring networks," in the IEEE Global Communications Conference (GLOBECOM), Miami, USA, Dec. 2010.

- Consider the game in *satisfaction form*:

$$\bar{\mathcal{G}} = (\mathcal{K}, \{\mathcal{A}_k\}_{k \in \mathcal{K}}, \{f_k\}_{k \in \mathcal{K}}) \quad (6)$$

- The notion of **utility maximization** or **cost minimization** does not exist.

Definition (Satisfaction Equilibrium)

An action profile \mathbf{a}^+ is a satisfaction equilibrium of $\bar{\mathcal{G}}$ if $\forall k \in \mathcal{K}$,

$$a_k^+ \in f_k(\mathbf{a}_k^+). \quad (7)$$

Satisfaction Equilibrium

Perlaza, S. M. and Tembine, H. and Lasaulce, S. and M. Debbah, “**Satisfaction equilibrium: A general framework for QoS provisioning in self-configuring networks,**” in the IEEE Global Communications Conference (GLOBECOM), Miami, USA, Dec. 2010.

- Consider the game in *satisfaction form*:

$$\bar{\mathcal{G}} = (\mathcal{K}, \{\mathcal{A}_k\}_{k \in \mathcal{K}}, \{f_k\}_{k \in \mathcal{K}}) \quad (6)$$

- The notion of **utility maximization** or **cost minimization** does not exist.

Definition (Satisfaction Equilibrium)

An action profile \mathbf{a}^+ is a satisfaction equilibrium of $\bar{\mathcal{G}}$ if $\forall k \in \mathcal{K}$,

$$a_k^+ \in f_k(\mathbf{a}_k^+). \quad (7)$$

Satisfaction Equilibrium

Perlaza, S. M. and Tembine, H. and Lasaulce, S. and M. Debbah, "Satisfaction equilibrium: A general framework for QoS provisioning in self-configuring networks," in the IEEE Global Communications Conference (GLOBECOM), Miami, USA, Dec. 2010.

- Consider the game in *satisfaction form*:

$$\bar{\mathcal{G}} = (\mathcal{K}, \{\mathcal{A}_k\}_{k \in \mathcal{K}}, \{f_k\}_{k \in \mathcal{K}}) \quad (6)$$

- The notion of **utility maximization** or **cost minimization** does not exist.

Definition (Satisfaction Equilibrium)

An action profile \mathbf{a}^+ is a satisfaction equilibrium of $\bar{\mathcal{G}}$ if $\forall k \in \mathcal{K}$,

$$\mathbf{a}_k^+ \in f_k(\mathbf{a}_k^+). \quad (7)$$

SE is a generalization of NE

Perlaza, S. M. and Tembine, H. and Lasaulce, S. and Debbah, M., "A General Framework for Quality-Of-Service Provisioning in Decentralized Networks". Submitted to the IEEE Journal in Selected Topics in Signal Processing, Special Issue in Game Theory for Signal Processing. 2011

- Consider the games in NF and SF

$$\mathcal{G} = (\mathcal{K}, \{\mathcal{A}_k\}_{k \in \mathcal{K}}, \{u_k\}_{k \in \mathcal{K}})$$

and

$$\bar{\mathcal{G}} = (\mathcal{K}, \{\mathcal{A}_k\}_{k \in \mathcal{K}}, \{f_k\}_{k \in \mathcal{K}}).$$

- Let the correspondence f_k be defined as follows:

$$f_k(\mathbf{a}_{-k}) = \text{BR}_k(\mathbf{a}_{-k}) = \arg \max_{a_k \in \mathcal{A}_k} u_k(a_k, \mathbf{a}_{-k}) \quad (8)$$

- Then, the set of SE of $\bar{\mathcal{G}}$ and the set of NE of \mathcal{G} coincide.

Let $\mathbf{a} \in \mathcal{A}$ be a NE. Then,

$$\mathbf{a} \in \text{BR}(\mathbf{a}), \quad (9)$$

where, $\text{BR}(\mathbf{a}) = \text{BR}_1(\mathbf{a}_{-1}) \times \dots \times \text{BR}_K(\mathbf{a}_{-K})$.

SE is a generalization of NE

Perlaza, S. M. and Tembine, H. and Lasaulce, S. and Debbah, M., "A General Framework for Quality-Of-Service Provisioning in Decentralized Networks". Submitted to the IEEE Journal in Selected Topics in Signal Processing, Special Issue in Game Theory for Signal Processing. 2011

- Consider the games in NF and SF

$$\mathcal{G} = (\mathcal{K}, \{\mathcal{A}_k\}_{k \in \mathcal{K}}, \{u_k\}_{k \in \mathcal{K}})$$

and

$$\bar{\mathcal{G}} = (\mathcal{K}, \{\mathcal{A}_k\}_{k \in \mathcal{K}}, \{f_k\}_{k \in \mathcal{K}}).$$

- Let the correspondence f_k be defined as follows:

$$f_k(\mathbf{a}_{-k}) = \text{BR}_k(\mathbf{a}_{-k}) = \arg \max_{a_k \in \mathcal{A}_k} u_k(a_k, \mathbf{a}_{-k}) \quad (8)$$

- Then, the set of SE of $\bar{\mathcal{G}}$ and the set of NE of \mathcal{G} coincide.

Let $\mathbf{a} \in \mathcal{A}$ be a NE. Then,

$$\mathbf{a} \in \text{BR}(\mathbf{a}), \quad (9)$$

where, $\text{BR}(\mathbf{a}) = \text{BR}_1(\mathbf{a}_{-1}) \times \dots \times \text{BR}_K(\mathbf{a}_{-K})$.

SE is a generalization of NE

Perlaza, S. M. and Tembine, H. and Lasaulce, S. and Debbah, M., "A General Framework for Quality-Of-Service Provisioning in Decentralized Networks". Submitted to the IEEE Journal in Selected Topics in Signal Processing, Special Issue in Game Theory for Signal Processing, 2011

- Consider the games in NF and SF

$$\mathcal{G} = (\mathcal{K}, \{\mathcal{A}_k\}_{k \in \mathcal{K}}, \{u_k\}_{k \in \mathcal{K}})$$

and

$$\bar{\mathcal{G}} = (\mathcal{K}, \{\mathcal{A}_k\}_{k \in \mathcal{K}}, \{f_k\}_{k \in \mathcal{K}}).$$

- Let the correspondence f_k be defined as follows:

$$f_k(\mathbf{a}_{-k}) = \text{BR}_k(\mathbf{a}_{-k}) = \arg \max_{a_k \in \mathcal{A}_k} u_k(a_k, \mathbf{a}_{-k}) \quad (8)$$

- Then, **the set of SE of $\bar{\mathcal{G}}$ and the set of NE of \mathcal{G} coincide.**

Let $\mathbf{a} \in \mathcal{A}$ be a NE. Then,

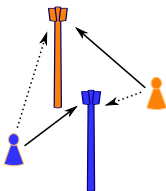
$$\mathbf{a} \in \text{BR}(\mathbf{a}), \quad (9)$$

where, $\text{BR}(\mathbf{a}) = \text{BR}_1(\mathbf{a}_{-1}) \times \dots \times \text{BR}_K(\mathbf{a}_{-K})$.

Example 2

2 Tx-Rx Pairs sharing 2 freq. band:

- **Minimum rate** required:
 Γ_k bps.
- N_k **Transmit Power Levels.**



- Players $\mathcal{K} = \{1, 2\}$.
- Actions: **Channel Selection**

$$\mathcal{A}_k = \{(p_{k,\max}, 0), (0, p_{k,\max})\}.$$

- Constraints:

$$\hat{u}_k(\mathbf{p}_k, \mathbf{p}_{-k}) = \sum_{s=1}^S \log_2 \left(1 + \frac{p_{k,s} |h_{k,k}^{(s)}|^2}{\sigma_k^2 + \sum_{j \neq k}^K p_{-k,s} |h_{k,-k}^{(s)}|^2} \right) [\text{bps}],$$

$$f_k(\mathbf{p}_{-k}) = \{p_k \in \mathcal{A}_k : u_k(\mathbf{p}_k, \mathbf{p}_{-k}) \geq \Gamma_k\}$$

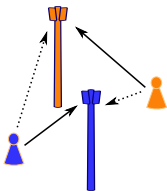
- Utility Function

$$u_k(\mathbf{p}_k, \mathbf{p}_{-k}) = \mathbb{1}_{\{p_k \in f_k(\mathbf{p}_{-k})\}}.$$

Example 2

2 Tx-Rx Pairs sharing 2 freq. band:

- **Minimum rate** required: Γ_k bps.
- N_k **Transmit Power Levels.**



$P_1 \setminus P_2$	$A_2^{(1)}$	$A_2^{(2)}$
$A_1^{(1)}$	(0, 0)	(1, 1)
$A_1^{(2)}$	(1, 0)	(0, 0)

Figure: Player 1 chooses rows and player 2 chooses columns.

- 2 NE in \mathcal{G} : $(A_1^{(2)}, A_2^{(1)})$ and $(A_1^{(1)}, A_2^{(2)})$,
- 1 SE in $\bar{\mathcal{G}}$: $(A_1^{(1)}, A_2^{(2)})$.

Example 2

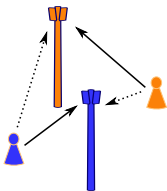
2 Tx-Rx Pairs sharing 2 freq. band:

- **Minimum rate** required:
 Γ_k bps.
- N_k **Transmit Power Levels.**

- In these particular games,

$$\mathcal{A}_{SE} \subseteq \mathcal{A}_{NE} \subseteq \mathcal{A}. \quad (10)$$

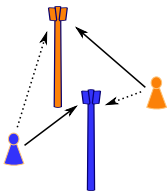
- At NE, all players might not be satisfied.
- At SE, if it exists, all players are satisfied.



Example 2

2 Tx-Rx Pairs sharing 2 freq. band:

- **Minimum rate** required:
 Γ_k bps.
- N_k **Transmit Power Levels.**



- In these particular games,

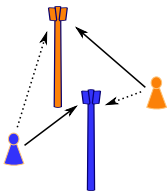
$$\mathcal{A}_{SE} \subseteq \mathcal{A}_{NE} \subseteq \mathcal{A}. \quad (10)$$

- At NE, **all players might not be satisfied.**
- At SE, if it exists, **all players are satisfied.**

Example 2

2 Tx-Rx Pairs sharing 2 freq. band:

- **Minimum rate** required:
 Γ_k bps.
- N_k **Transmit Power Levels.**



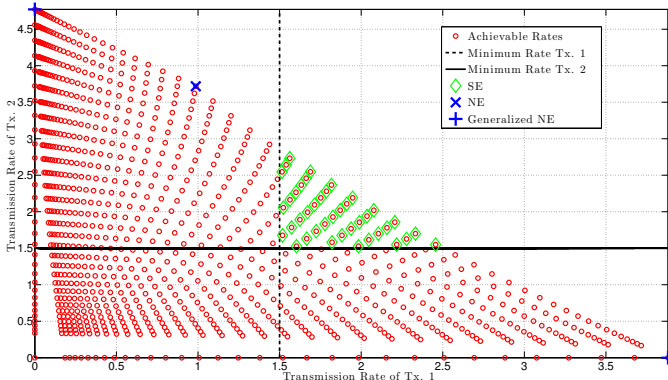
- In these particular games,

$$\mathcal{A}_{SE} \subseteq \mathcal{A}_{NE} \subseteq \mathcal{A}. \quad (10)$$

- At NE, **all players might not be satisfied.**
- At SE, if it exists, **all players are satisfied.**

Example 1

Achievable Rates + Minimum Rates + NE + GNE + SE



Neither the NE nor GNE properly model the QoS provisioning problem.

Does a SE always exist?

Let the correspondence $F : \mathcal{A} \rightarrow 2^{\mathcal{A}}$ be defined as follows:

$$F(\mathbf{a}) = f_1(\mathbf{a}_{-1}) \times \dots \times f_K(\mathbf{a}_{-K}).$$

Then, an SE exists if and only if

$$\exists \mathbf{a} \in \mathcal{A} : \mathbf{a} \in F(\mathbf{a}). \quad (11)$$

This formulation is a **fixed point inclusion!**

Proposition (Existence of the SE (Kakutani-1941))

*In the game $\bar{g} = (\mathcal{K}, \{\mathcal{A}_k\}_{k \in \mathcal{K}}, \{f_k\}_{k \in \mathcal{K}})$, let the set of actions \mathcal{A} be a **non-empty, convex and compact set**. Let also the correspondence $F(\mathbf{a})$ have a **closed graph** and be **non-empty and convex** in the set of actions \mathcal{A} . Then, the game \bar{g} has at least one SE.*

Does a SE always exist?

Let the correspondence $F : \mathcal{A} \rightarrow 2^{\mathcal{A}}$ be defined as follows:

$$F(\mathbf{a}) = f_1(\mathbf{a}_{-1}) \times \dots \times f_K(\mathbf{a}_{-K}).$$

Then, an SE exists if and only if

$$\exists \mathbf{a} \in \mathcal{A} : \mathbf{a} \in F(\mathbf{a}). \quad (11)$$

This formulation is a **fixed point inclusion!**

Proposition (Existence of the SE (Kakutani-1941))

*In the game $\bar{g} = (\mathcal{K}, \{\mathcal{A}_k\}_{k \in \mathcal{K}}, \{f_k\}_{k \in \mathcal{K}})$, let the set of actions \mathcal{A} be a **non-empty, convex and compact set**. Let also the correspondence $F(\mathbf{a})$ have a **closed graph** and be **non-empty and convex** in the set of actions \mathcal{A} . Then, the game \bar{g} has at least one SE.*

Does a SE always exist?

Let the correspondence $F : \mathcal{A} \rightarrow 2^{\mathcal{A}}$ be defined as follows:

$$F(\mathbf{a}) = f_1(\mathbf{a}_{-1}) \times \dots \times f_K(\mathbf{a}_{-K}).$$

Then, an SE exists if and only if

$$\exists \mathbf{a} \in \mathcal{A} : \mathbf{a} \in F(\mathbf{a}). \quad (11)$$

This formulation is a **fixed point inclusion!**

Proposition (Existence of the SE (Kakutani-1941))

*In the game $\bar{\mathcal{G}} = (\mathcal{K}, \{\mathcal{A}_k\}_{k \in \mathcal{K}}, \{f_k\}_{k \in \mathcal{K}})$, let the set of actions \mathcal{A} be a **non-empty, convex and compact set**. Let also the correspondence $F(\mathbf{a})$ have a **closed graph** and be **non-empty** and **convex** in the set of actions \mathcal{A} . Then, the game $\bar{\mathcal{G}}$ has at least one SE.*

Existence of the SE

Many results from Fixed Point Inclusions are available:

- S. Kakutani, “A generalization of Brouwer’s fixed point theorem”, Duke Mathematical Journal, vol. 8, pp. 457–459, 1941.
- B. Knaster and A. Tarski, “Un théorème sur les fonctions d’ensembles,” Ann. Soc. Polon. Math., vol. 6, pp. 133–134, 1928
- K. C. Border, Fixed Point Theorems with Applications to Economics and Game Theory. New York, NY, USA: Cambridge University Press, 1985.

Uniqueness of the SE

Perlaza, S. M. and Tembine, H. and Lasaulce, S. and Debbah, M., "**A General Framework for Quality-Of-Service Provisioning in Decentralized Networks**". Submitted to the IEEE Journal in Selected Topics in Signal Processing. Special Issue in Game Theory for Signal Processing. 2011

- A SE is in general **not unique**.
- Which action to play to be satisfied?
(**Effort for Satisfaction**)
- How to select a SE? (**Efficient SE**)

Uniqueness of the SE

Perlaza, S. M. and Tembine, H. and Lasaulce, S. and Debbah, M., "**A General Framework for Quality-Of-Service Provisioning in Decentralized Networks**". Submitted to the IEEE Journal in Selected Topics in Signal Processing. Special Issue in Game Theory for Signal Processing. 2011

- A SE is in general **not unique**.
- Which action to play to be satisfied?
(Effort for Satisfaction)
- How to select a SE? **(Efficient SE)**

Uniqueness of the SE

Perlaza, S. M. and Tembine, H. and Lasaulce, S. and Debbah, M., "**A General Framework for Quality-Of-Service Provisioning in Decentralized Networks**". Submitted to the IEEE Journal in Selected Topics in Signal Processing. Special Issue in Game Theory for Signal Processing. 2011

- A SE is in general **not unique**.
- Which action to play to be satisfied?
(**Effort for Satisfaction**)
- How to select a SE? (**Efficient SE**)

Efficient Satisfaction Equilibrium

Perlaza, S. M. and Tembine, H. and Lasaulce, S. and Debbah, M., "A General Framework for Quality-Of-Service Provisioning in Decentralized Networks". Submitted to the IEEE Journal in Selected Topics in Signal Processing, Special Issue in Game Theory for Signal Processing, 2011

- The **set of ESE** of the game

$$\bar{\mathcal{G}} = (\mathcal{K}, \{\mathcal{A}_k\}_{k \in \mathcal{K}}, \{f_k\}_{k \in \mathcal{K}}),$$

w.r.t. the cost functions c_1, \dots, c_K , **coincides with the set of GNE** of the game

$$\tilde{\mathcal{G}} = (\mathcal{K}, \{\mathcal{A}_k\}_{k \in \mathcal{K}}, \{c_k\}_{k \in \mathcal{K}}, \{f_k\}_{k \in \mathcal{K}}).$$

- The game $\tilde{\mathcal{G}}$ is an **exact constrained potential game** (ECPG).

$$\text{Potential function: } \phi(\mathbf{a}) = \sum_{k=1}^K c_k(a_k). \quad (12)$$

- ECPGs **do not have the same properties** than Potential Games.
- **Existence, Uniqueness and convergence of the best response dynamics** are constrained.

Efficient Satisfaction Equilibrium

Perlaza, S. M. and Tembine, H. and Lasaulce, S. and Debbah, M., "A General Framework for Quality-Of-Service Provisioning in Decentralized Networks". Submitted to the IEEE Journal in Selected Topics in Signal Processing. Special Issue in Game Theory for Signal Processing. 2011

- The **set of ESE** of the game

$$\bar{\mathcal{G}} = (\mathcal{K}, \{\mathcal{A}_k\}_{k \in \mathcal{K}}, \{f_k\}_{k \in \mathcal{K}}),$$

w.r.t. the cost functions c_1, \dots, c_K , **coincides with the set of GNE** of the game

$$\tilde{\mathcal{G}} = (\mathcal{K}, \{\mathcal{A}_k\}_{k \in \mathcal{K}}, \{c_k\}_{k \in \mathcal{K}}, \{f_k\}_{k \in \mathcal{K}}).$$

- The game $\tilde{\mathcal{G}}$ is an **exact constrained potential game** (ECPG).

$$\text{Potential function: } \phi(\mathbf{a}) = \sum_{k=1}^K c_k(a_k). \quad (12)$$

- ECPGs do not have the same properties than Potential Games.
- Existence, Uniqueness and convergence of the best response dynamics are constrained.

Efficient Satisfaction Equilibrium

Perlaza, S. M. and Tembine, H. and Lasaulce, S. and Debbah, M., "A General Framework for Quality-Of-Service Provisioning in Decentralized Networks". Submitted to the IEEE Journal in Selected Topics in Signal Processing. Special Issue in Game Theory for Signal Processing. 2011

- The **set of ESE** of the game

$$\bar{\mathcal{G}} = (\mathcal{K}, \{\mathcal{A}_k\}_{k \in \mathcal{K}}, \{f_k\}_{k \in \mathcal{K}}),$$

w.r.t. the cost functions c_1, \dots, c_K , **coincides with the set of GNE** of the game

$$\tilde{\mathcal{G}} = (\mathcal{K}, \{\mathcal{A}_k\}_{k \in \mathcal{K}}, \{c_k\}_{k \in \mathcal{K}}, \{f_k\}_{k \in \mathcal{K}}).$$

- The game $\tilde{\mathcal{G}}$ is an **exact constrained potential game** (ECPG).

$$\text{Potential function: } \phi(\mathbf{a}) = \sum_{k=1}^K c_k(a_k). \quad (12)$$

- ECPGs **do not have the same properties** than Potential Games.
- **Existence, Uniqueness and convergence of the best response dynamics** are constrained.

Efficient Satisfaction Equilibrium

Perlaza, S. M. and Tembine, H. and Lasaulce, S. and Debbah, M., "A General Framework for Quality-Of-Service Provisioning in Decentralized Networks". Submitted to the IEEE Journal in Selected Topics in Signal Processing. Special Issue in Game Theory for Signal Processing. 2011

- The **set of ESE** of the game

$$\bar{\mathcal{G}} = (\mathcal{K}, \{\mathcal{A}_k\}_{k \in \mathcal{K}}, \{f_k\}_{k \in \mathcal{K}}),$$

w.r.t. the cost functions c_1, \dots, c_K , **coincides with the set of GNE** of the game

$$\tilde{\mathcal{G}} = (\mathcal{K}, \{\mathcal{A}_k\}_{k \in \mathcal{K}}, \{c_k\}_{k \in \mathcal{K}}, \{f_k\}_{k \in \mathcal{K}}).$$

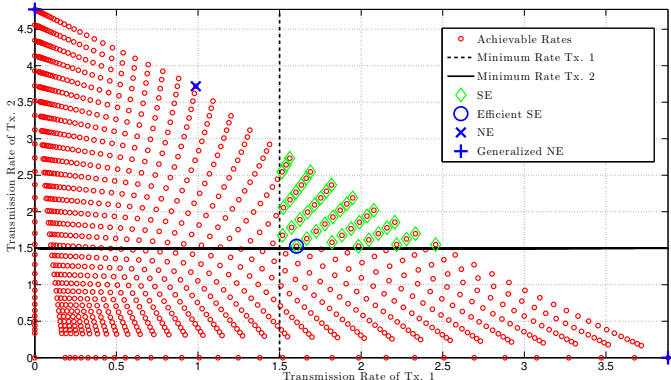
- The game $\tilde{\mathcal{G}}$ is an **exact constrained potential game** (ECPG).

$$\text{Potential function: } \phi(\mathbf{a}) = \sum_{k=1}^K c_k(a_k). \quad (12)$$

- ECPGs **do not have the same properties** than Potential Games.
- **Existence, Uniqueness** and **convergence of the best response dynamics** are constrained.

Example 1

Achievable Rates + Minimum Rates + NE + GNE + SE + ESE

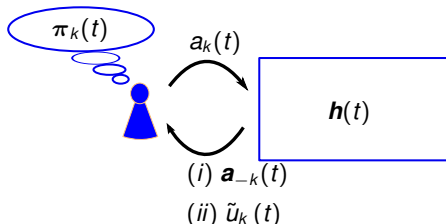


At ESE all players are satisfied by doing a **minimum effort**.

Learning Satisfaction Equilibria

Learning Iterative Steps:

- **Choose** action $a_k(t) \sim \pi_k(t)$.
- **Observe** game outcome, e.g.,
 $\mathbf{a}_{-k}(t)$
 $u_k(a_k(t), \mathbf{a}_{-k}(t))$.
- **Improve** $\pi_k(t+1)$.



Thus, we can expect that: $\forall k \in \mathcal{K}$,

$$a_k(t) \xrightarrow{t \rightarrow \infty} \mathbf{a}_k^*, \quad (13)$$

where, $\mathbf{a}^* = (\mathbf{a}_1^*, \dots, \mathbf{a}_K^*)$ is a SE action profile.

Learning Satisfaction Equilibria

S. Ross and B. Chaib-draa, "Learning to play a satisfaction equilibrium." in *Workshop on Evolutionary Models of Collaboration*, 2007.

- 1 Observation at iteration t :

$$\tilde{u}_k(t) = \begin{cases} 1 & \text{if } \mathbf{a}_k(t) \in f_k(\mathbf{a}_{-k}(t)) \\ 0 & \text{otherwise.} \end{cases}$$

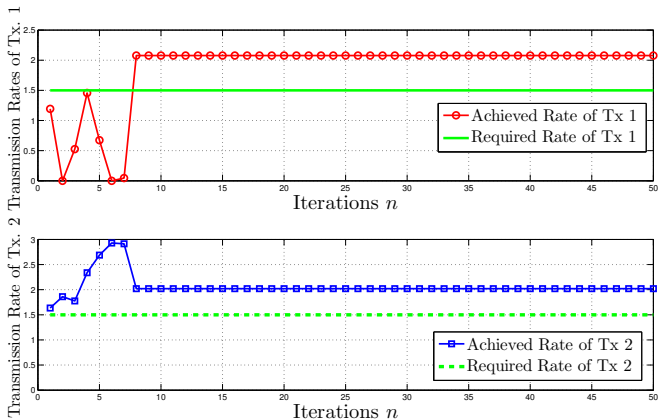
- 2 Action at iteration t :

$$\mathbf{a}_k(t) = \begin{cases} \mathbf{a}_k(t-1) & \text{if } \tilde{v}_k(t) = 1 \\ \mathbf{a}_k(t) \sim \pi_k(t) & \text{otherwise.} \end{cases} \quad (14)$$

- 3 Strategy at iteration t : $\pi_k(t) = \left(\pi_{k, A_k^{(1)}}(t), \dots, \pi_{k, A_k^{(N_k)}}(t) \right)$,

$$\forall n_k \in \{1, \dots, N_k\}, \quad \hat{\pi}_{k, A_k^{(n_k)}}(n) = \frac{1}{N_k}. \quad (15)$$

Example 1



Learning Satisfaction Equilibria

Definition (Clipping Action)

A player k is said to have a clipping action $a_k \in \mathcal{A}_k$ in the game

$\bar{\mathcal{G}} = (\mathcal{K}, \{\mathcal{A}_k\}_{k \in \mathcal{K}}, \{f_k\}_{k \in \mathcal{K}})$ if

$$\forall \mathbf{a}_{-k} \in \mathcal{A}_{-k}, \quad a_k \in f_k(\mathbf{a}_{-k}). \quad (16)$$

Proposition

Let $a_k^* \in \mathcal{A}_k$ be a clipping strategy for player k . Then, if there exists a player $j \in \mathcal{K} \setminus \{k\}$, and an action profile $(a_k^*, \cdot) \in \mathcal{A}_{-j}$ for which $f_j(a_k^*, \cdot) = \emptyset$. Then, the behavioral rule in (14) does not converge to a SE with strictly positive probability.

Learning Satisfaction Equilibria

Definition (Clipping Action)

A player k is said to have a clipping action $a_k \in \mathcal{A}_k$ in the game

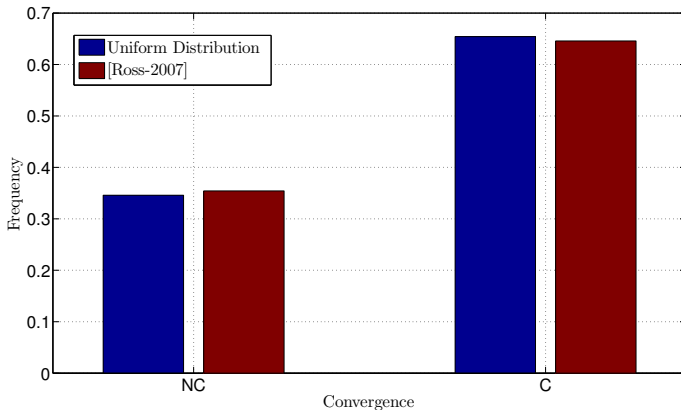
$\bar{\mathcal{G}} = (\mathcal{K}, \{\mathcal{A}_k\}_{k \in \mathcal{K}}, \{f_k\}_{k \in \mathcal{K}})$ if

$$\forall \mathbf{a}_{-k} \in \mathcal{A}_{-k}, \quad a_k \in f_k(\mathbf{a}_{-k}). \quad (16)$$

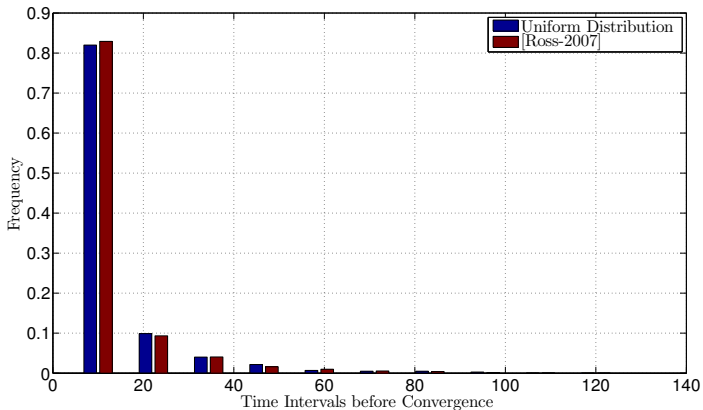
Proposition

Let $a_k^* \in \mathcal{A}_k$ be a clipping strategy for player k . Then, if there exists a player $j \in \mathcal{K} \setminus \{k\}$, and an action profile $(a_k^*, \cdot) \in \mathcal{A}_{-j}$ for which $f_j(a_k^*, \cdot) = \emptyset$. Then, the behavioral rule in (14) does not converge to a SE with strictly positive probability.

Example 1



Example 1



Conclusions

- A suitable equilibrium for **QoS provisioning in small cells** exists.
- Learning Dynamics for **achieving SE** have been presented.
- Several **convergence issues** remain to be solved in SE.
- Learning Dynamics for **achieving ESE** are still unknown.

Further Work ...

- What if no SE exists? ϵ -**SE**.
- How to overcome a Clipping Action? **Trial and Error Learning**.
- How to achieve an ESE?

Further Work ...

- What if no SE exists? ϵ -**SE**.
- How to overcome a Clipping Action? **Trial and Error Learning**.
- How to achieve an ESE?

Further Work ...

- What if no SE exists? ϵ -**SE**.
- How to overcome a Clipping Action? **Trial and Error Learning**.
- How to achieve an ESE?